





La Digitalització de la Mobilitat

Data Science i Intel·ligència artificial

Eduardo Quiñones
Barcelona Supercomputing Center
(BSC)





Introduction

Barcelona Supercomputing Center — Centro Nacional de Supercomputación (BSC-CNS)

 Public research center focused on the research and efficient used of supercomputing technologies applied to science, society and economy



Eduardo Quiñones

- PhD in Computer Science by Technical University of Catalonia (UPC)
- Team leader of the *Predictable Parallel Computing* research group
- Principal Investigator (PI) of several European and national projects related to mobility



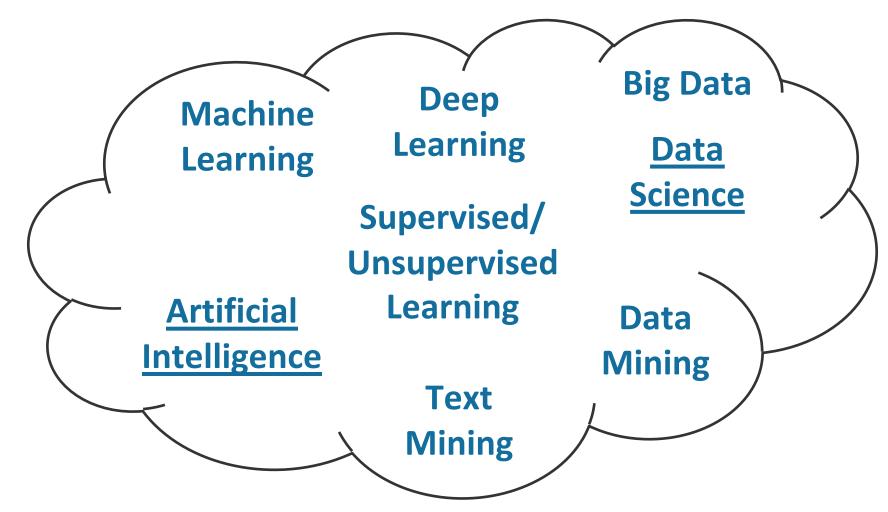








Data Science and Artificial Intelligence (AI)





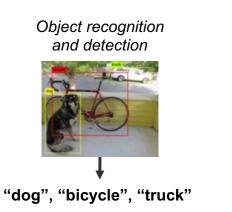


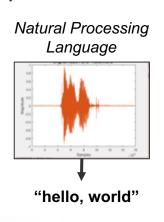




Data Science and Artificial Intelligence (AI)

- Data Science focuses on the analysis of data sources across all data value chain to <u>extract information (knowledge)</u> upon which decisions can be taken
- Al focuses on providing to computers the capability to percieve, learn and reason about data to perform a specific task
 - There are not systems with Artificial General Intelligence











Data Analysis

Data Provisioning

> Data Enrichment

Data Ingestion

Data

Authoring









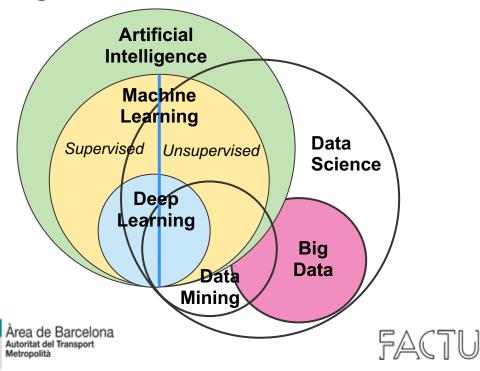
Data Science and Artificial Intelligence

Data Science

- Data Mining: Set of data analytics methods for knoweldge extraction
 - Visualization, data cleaning, AI model training
- Big Data: Set of storage and computation technologies used to process huge amounts of data

Artificial Intelligence

- Machine Learning
- Supervised/Unsupervised Learning
- Deep Learning







Objective of the Seminar

- Understand the AI methods that can be used to enhance urban mobility and identify the main threads of AI
- 2. Applying Data Science and AI to Urban Mobility
- 3. Data Science and AI in cities from a computing/communication perspective: Edge and Cloud Computing









1. Artificial Intelligence

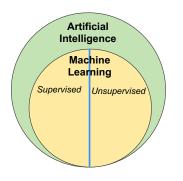








Machine Learning: Supervised and Unsupervised



"The field of study that gives computers the ability to learn without being explicitly programmed" (Arthur Samuel, 1959)

Al models are built upon <u>representative sample data</u> (training data) including the knowledge require to perform an specific action

- Training phase: The process of building the model based on a training data-set
 - Supervised learning: The training data-set is known and predefined
 - **Unsupervised learning:** The model is trained in operational environment, based on an objective function
- Inference phase: The process of performing the action for what the model has been designed, based on an input data





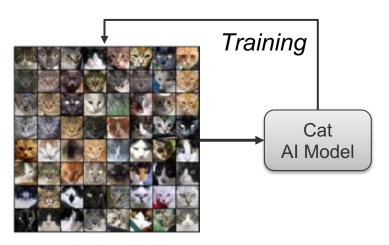


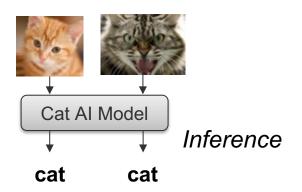


Machine Learning: Supervised and Unsupervised

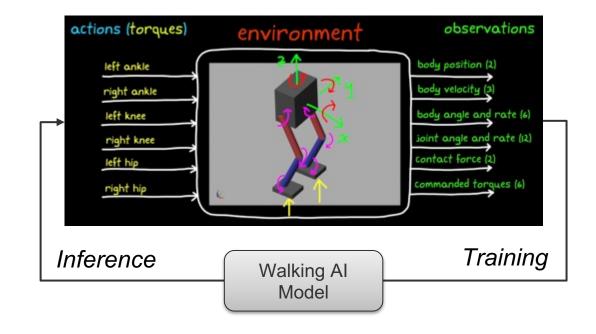
Artificial Intelligence Machine Learning Supervised Unsupervised

Supervised





Unsupervised



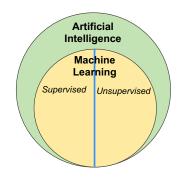








Machine Learning: Supervised and Unsupervised





Learning to walk
with unsupervised
machine learning
(deep reinforcement
learning)

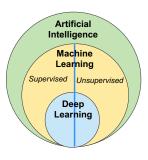




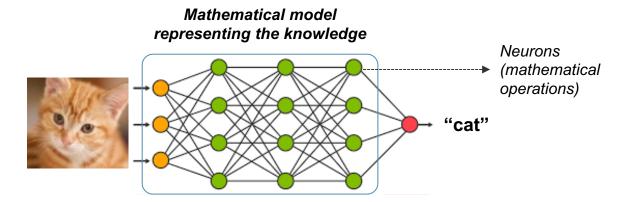




Deep Learning



- The knowledge is represented in the form of <u>artificial neural networks</u> (ANN) or deep neural networks (DNN)
 - Inspired on how the information is processed by the brain



- Firstly proposed in 1967 by Ivakhnenko and Lapa
- In 2010, the use of Graphical Processing Units (GPUs) speed the training processes

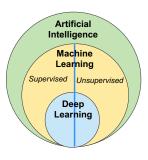




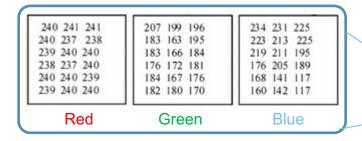


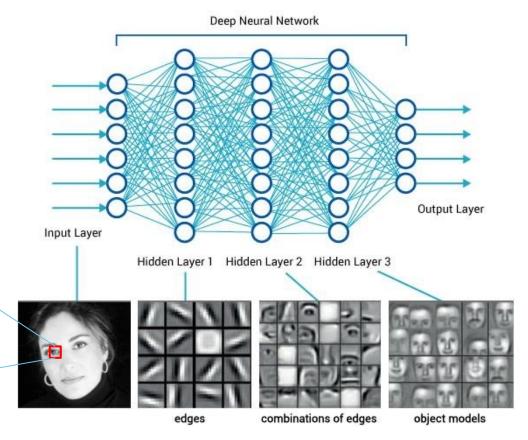


Deep Learning



- Artificial Neural Networks layers are responsible of extracting different features of the data
 - Hierarchical representation of information





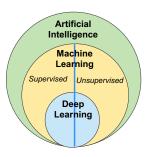




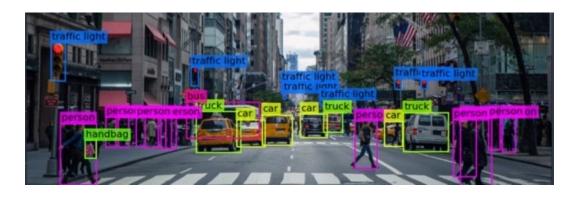




Object Detection with Deep Learning



- Key functionality to perceive urban scenarios upon which decisions can be taken
 - Different models are used for different purposes















Object Detection with Deep Learning: Threads and Limitations

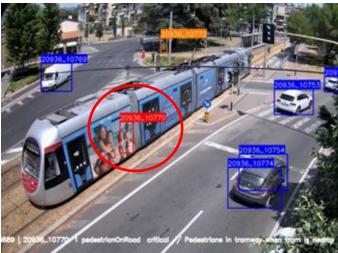
Artificial Intelligence

Machine Learning
Supervised
Unsupervised

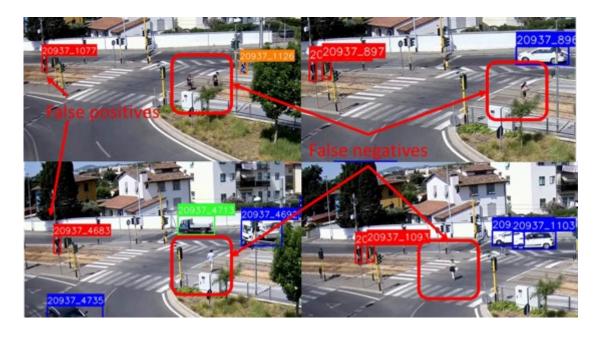
Deep Learning

- False positives
 - Motorcycles and bicycles detected as pedestrians
 - Tram commercials detected as pedestrians
 - Traffic signs detected as pedestrians





- False negatives
 - Detection failing due to light, obstructions, perspective, distance



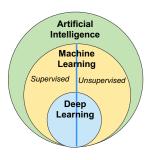




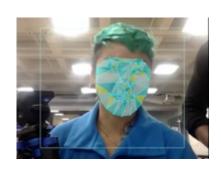




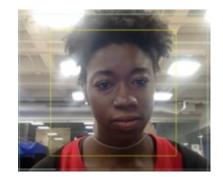
Object Detection with Deep Learning: Bias/Discrimation



Popular face detection systems <u>are not trained with</u> representative data to detect dark-skin people







https://youtu.be/TWWsW1w-BVo



Gender Shades project (http://gendershades.org)
evaluates the accuracy of Al powered gender
classification products









Object Detection with Deep Learning: Adversarial Attacks

Impercepcial changes in the input data (not visible by humans)









Artificial Intelligence Machine Learning

Supervised Unsupervised

Learning

"Hare"

"Desk"

"Stop sign"

"Max Speed 100"

 Physical changes on the input image



The T-shirt prevents the person to be detected





Face recognition



"Milla Jojovich"

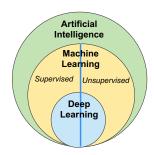


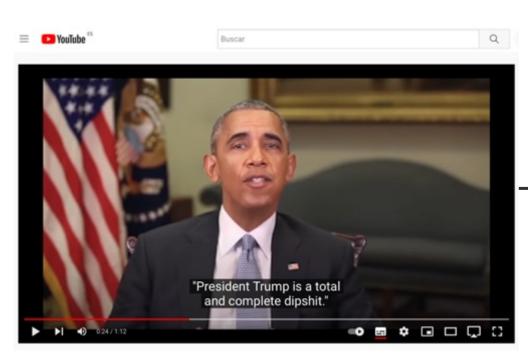






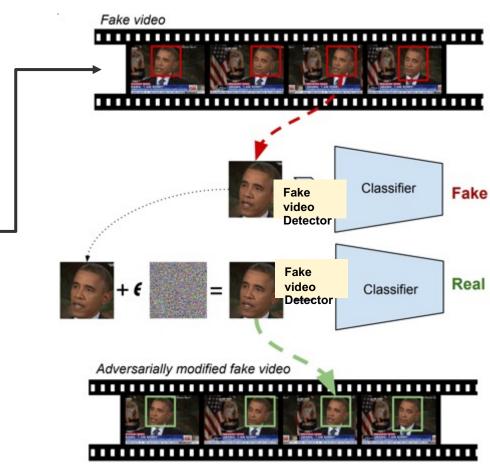
Object Detection with Deep Learning: Adversarial Attacks for Deep Fake Generation





https://youtu.be/cQ54GDm1eL0









Towards an Ethical and Secure Used of Al

- Understand the <u>specific task</u> for what the AI engine has been trained
 - 1. Ensure that the data-set used to train the AI model is <u>representative</u> for the intended task
 - 2. Ensure that the AI software method is appropriate for the task to be solved
 - Preferable to use open-source solutions
 - 3. Identify the security flaws of the data and the model
- Create <u>multi-disciplinary teams</u>

https://www.tesla.com/autopilot?redirect=no







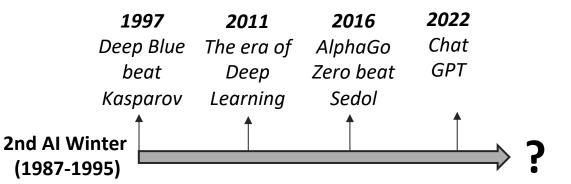


History of Al

1965, H. A. Simon: "machines will be capable, within twenty years, of doing any work a man can do"
1970, M. Minsky: "In from three to eight years we will have a machine with the general intelligence of an average human being"



2015 - 2016, BMW, GM, VW, Tesla: "Autonomous vehicles will be on the road on 2020"











Debate about AI and Ethics at Oxford Union Society (Dec 2021)

"AI will never be ethical. It is a tool, and like any tool, it is used for good and bad. There is no such thing as a good AI, only good and bad humans. We are not smart enough to make AI ethical. We are not smart enough to make AI moral ... In the end, I believe that the only way to avoid an AI arms race is to have no AI at all. This will be the ultimate defense against AI"



Al engine (Megatron Transformer) trained with the whole Wikipedia, 63 million English news articles from 2016 to 2019, and 38 GB of public Reddit posts and comments









2. Applying Data Science and AI to Urban Mobility









Applying Data Science to Urban Mobility

- 1. Which knowledge do we want to extract?
 - How many times pedestrians crosses in red
- 2. Percepcion
 - Identify data sources
 - Identify the urban actors relevant for the service
 - The dynamics of each actor (e.g., static/moving element, speed, direction)
 - Provide semantic information to put each actor in the urban context



Piazza Batoni, Florence (Italy)

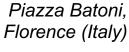




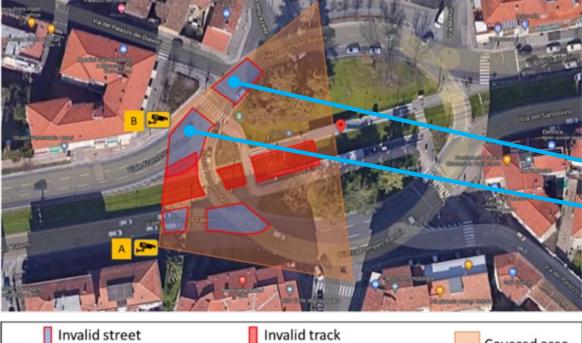




Semantic Information and **Data Sources**



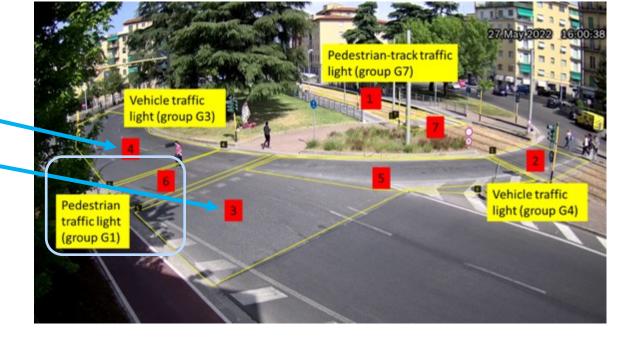




pedestrian crossings

pedestrian crossings

Covered area











Applying Data Science to Urban Mobility

- 1. Which knowledge do we want to extract?
 - How many times pedestrians crosses in red
- 2. Percepcion
 - Identify data sources
 - Identify the urban actors relevant for the analysis
 - The dynamics of each actor (e.g., static/moving element, speed, direction)
 - Provide semantic information to put each actor in the urban context



- For what do we want the knowledge?
- 4. Evaluation
 - Determine the extracted knowledge quality





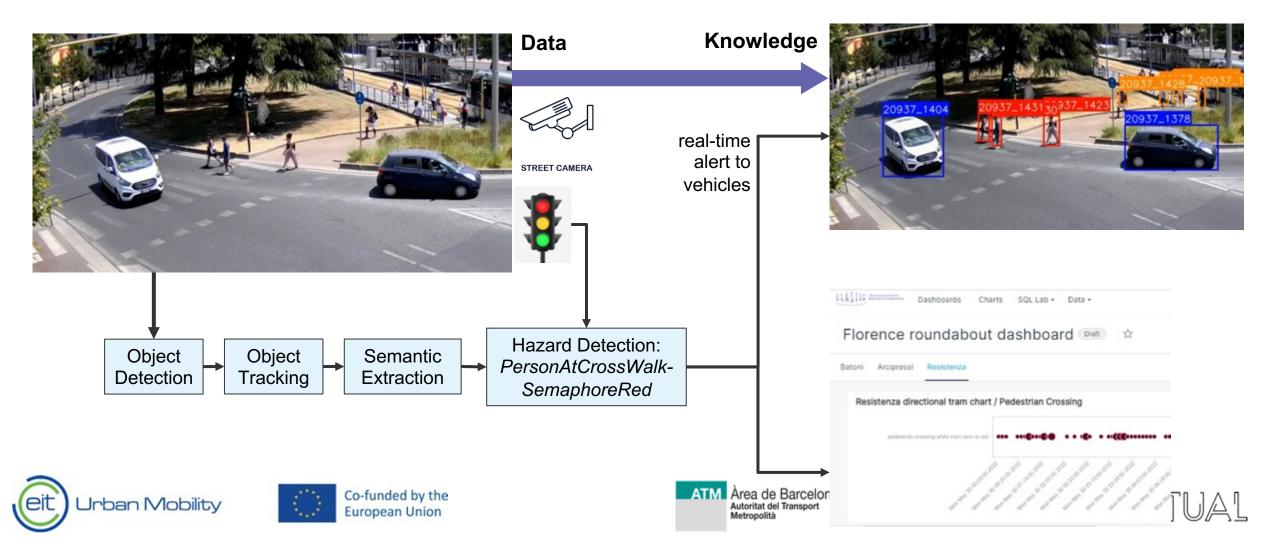


Piazza Batoni, Florence (Italy)





Pedestrians on the crosswalk when the traffic light is red

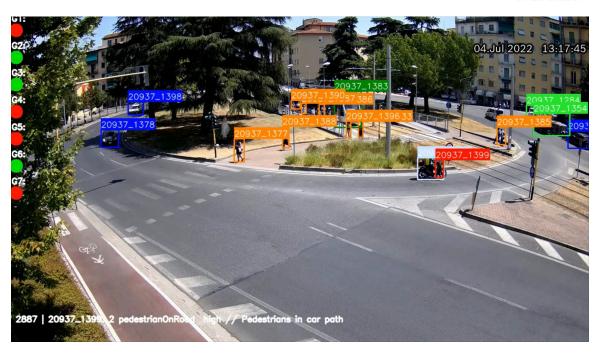


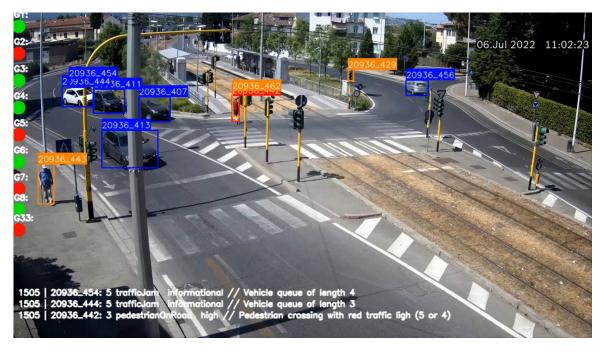
Pedestrians on the crosswalk when the traffic light is red











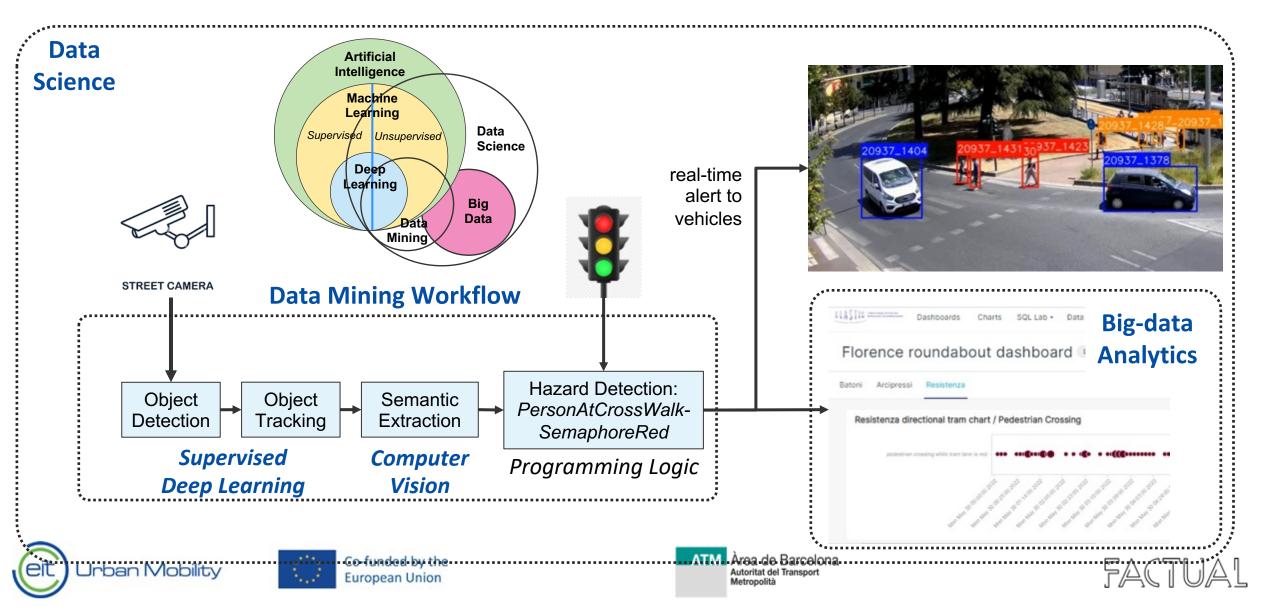






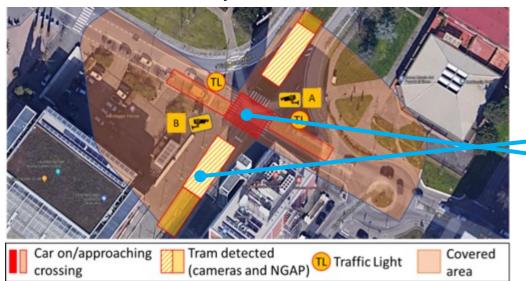


How many times pedestrians crosses in red?



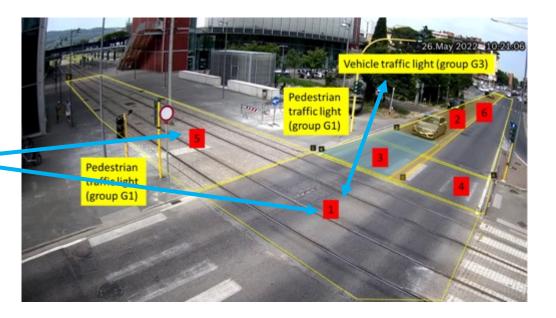
Pedestrians/cars crossing the rail tracks when tram approaching

- 1. Identify data sources
- 2. Provide semantic information
- 3. Identify the urban actors
- 4. Determine dynamics of actors

















Pedestrians/cars crossing the rail tracks when tram approaching



STREET CAMERA















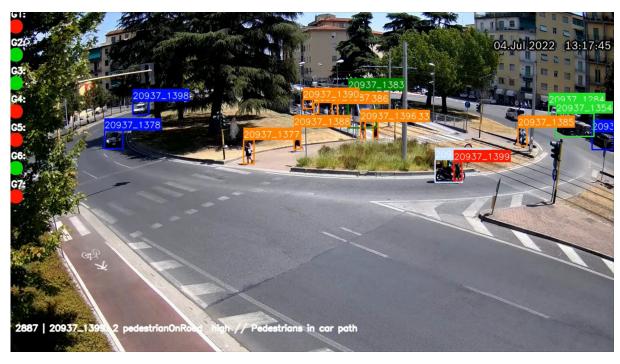




Pedestrians crossing the street outside designated areas















Traffic Queues





Vehicle traffic queue of length 11

Vehicle traffic queue of length 6









City-Car Interaction













Confusion matrix for each event of interest

- True Positives: true event detected
- False Negatives: true event not detected
- False Positives: no event but detected

Accuracy evaluation

$$Precision = \frac{True\ Positives}{True\ Positives + False\ Positives}$$

$$Recall = \frac{True\ Positives}{True\ Positives + False\ Negatives}$$

$$F1 = 2 \cdot \frac{Precision \cdot Recall}{Precision + Recall}$$

Refers to the portion of relevant events correctly detected among all **detected** events

Refers to the portion of relevant events correctly detected among all **relevant** events

A measure of event detection accuracy:

- F1 = 1 perfect detection
- F1 = 0 no detection





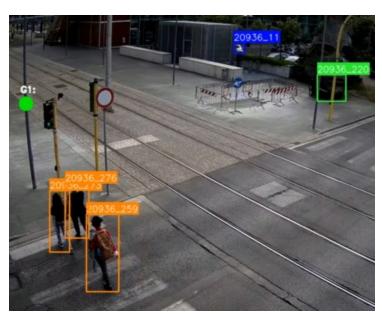


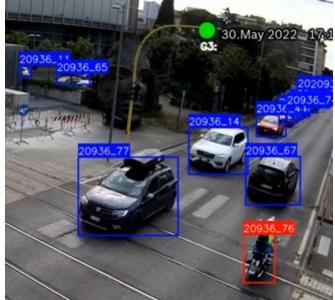


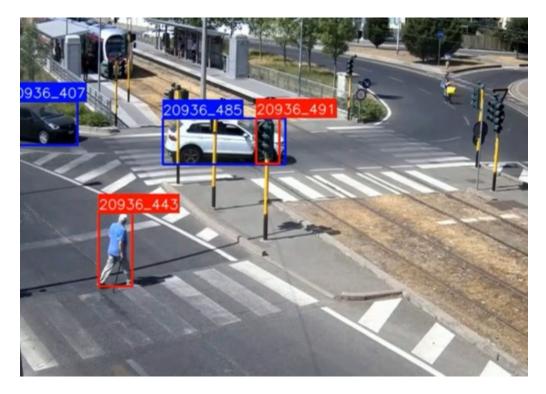
True Positives: true event detected

False Negatives: true event not detected

False Positives: no event but detected









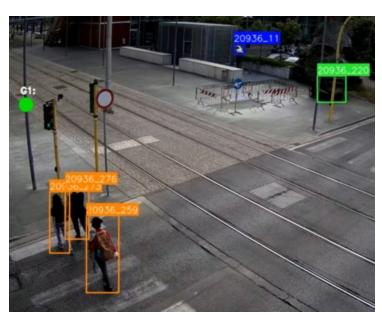


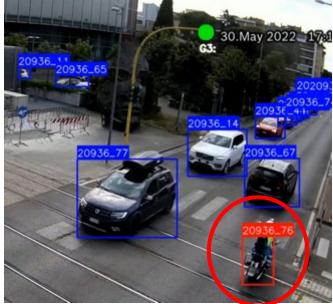


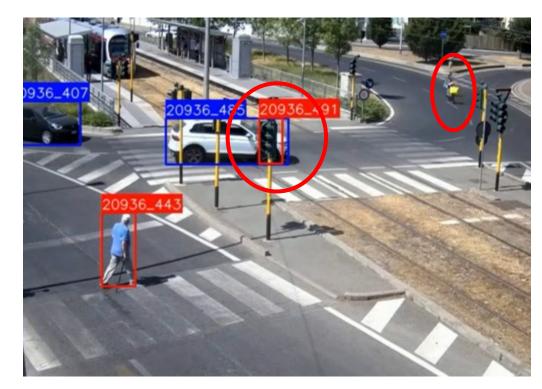




- (3) True Positives: true event detected
- (2) False Negatives: true event not detected
- (2) False Positives: no event but detected

















 Manual inspection of data sources (videos, semaphores, tram position) collected on <u>representative conditions</u>

Event	Precision	Recall	F1-score
P1 (pedestrians crossing tracks)	71%	98.6%	82.6%
P2 (pedestrians crossing street)	12.7%	100%	22.5%
P3 (pedestrians crossing with red)	62.2%	100%	76.7%

Event	Precision	Recall	F1-score
P1 (pedestrians crossing P2 (pedestrians crossing tracks)	28 ₁ 6% 5.1%	100%	44.44% 9.72%
P2 (pedestrians crossing P3 (pedestrians crossing street)	62.2%	65.22%	21.9% 76.7%
P3 (pedestrians crossing VI (vehicles approaching)	72.3% 68.2%	89.4%	80%%

P2 (pedestrians crossing Urban Street)

0

Co28 Med by the European Union 100%

43.8%/I Àrea de Barcelona Autoritat del Transport Metropolità

93.33%



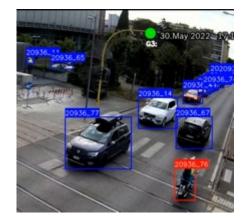
Evaluation Methodology

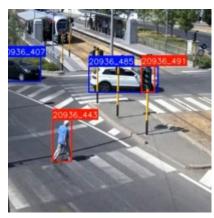
Manual inspection of data sources (videos, semaphores, tram position) collected on representative conditions

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P3 (pedestrians crossing / VI (vehicles approaching / with red)	<i>72.3</i> %	89.4% 100%	88.0%%

The DNN detects motocycles, bycicles and semaphores as pedestrians







Co28%ed by the **European Union**

100%



Camera B

Evaluation Methodology

Manual inspection of data sources (videos, semaphores, tram position)

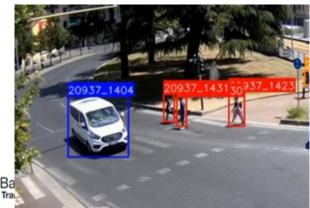
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Only peo	destriar	uses
crosswa	Iks and	tracks



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P2 (pedestrians crossing Urban Meet)ity

Camera B

0

Co28 Wed by the European Union

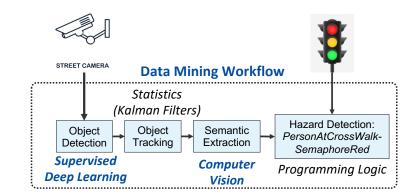
100%

43.89%/ Area de Autoritat del Metropolità

93.33%

FACTUAL

Actions to increase accuracy



- Improvement of object detection
 - Motorcycles, bicycles and traffic lights (currently identified as pedestrians)
 - Tram vehicles (currently identified as cars)
 - Used of dynamic properties of objects (speed, direction, etc.)
- More complex semantic rules can be applied for each specific event and captured area, targeting the issues identified in the quantitative analysis
 - Refine semantic annotation to filter out traffic signs, compensate for camera perspective
 - Use additional metrics, e.g., speed or trajectory to refine analytics









3. Data Science and AI in cities from a computing/communication perspective

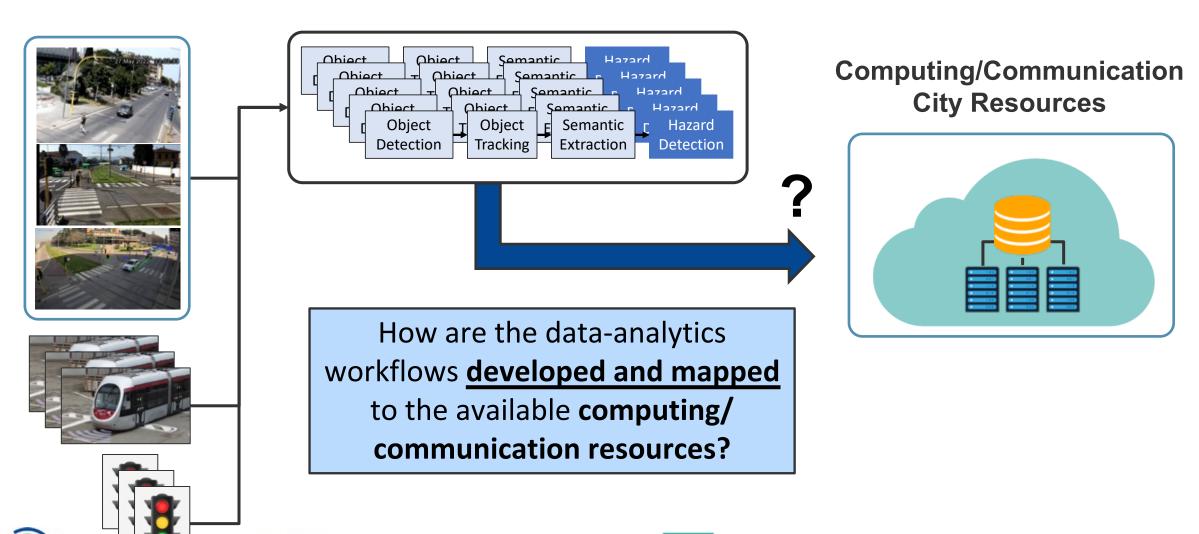








Data Mining Workflows and Computing Resources



Co-funded by the

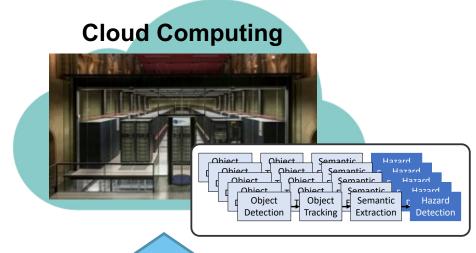
European Union





Centralised vs. Distribute

- Unsecure (single point of attack)
- Privacy Issues
- Inefficient in terms of energy and cost



Huge amounts of <u>sensitive</u> <u>information</u> are transmitted















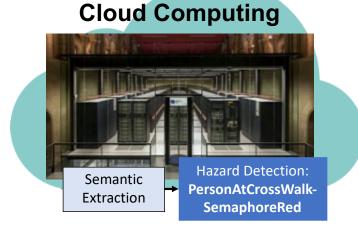






Centralised vs. Distribute: The Edge Computing

- More robust in terms of security
- Privacy is ensured
- Energy and cost efficiency



Much less <u>sensitive</u> <u>information</u> is transmitted



Edge Computing



Object Detection Object Tracking



Object Detection Object Tracking



Object Detection Object Tracking

















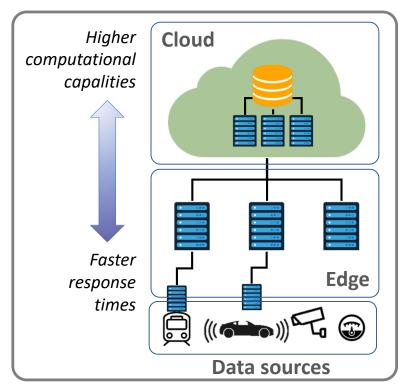






The Compute Continuum: Edge and Cloud

Compute Continuum



- Facilitate the development of complex data analytics workflows independently of the platform
- 2. Increase the capabilities of the data analytics by distributing them across the compute continuum
- 3. <u>Fulfill</u> the **non-functional requirements** inherited from the application domain, e.g., real-time, privacy



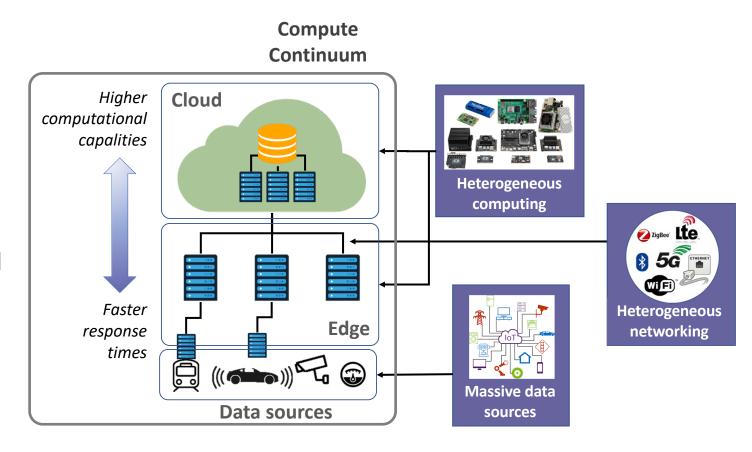






The Compute Continuum: Edge and Cloud

- There are not mature technical solutions capable of fully exploiting the capabilities of the compute continuum
- Very interesting research is still pending!
- Mobility experts will play a fundamental role











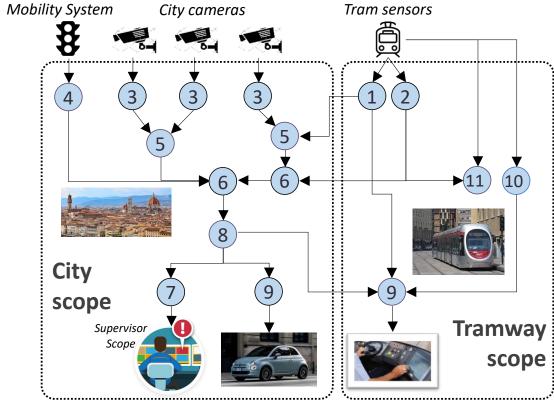
Complex Data Mining Workflows



A Software Architecture for Extreme-ScaLe
Big-Data AnalyticS in Fog CompuTIng Ecosystems

Data Analytics Methods

- 1. Sensor fusion (ADAS)
- 2. Tram position (NGAP)
- 3. Object detection, tracking & semantics
- 4. UTC/Supervisor consolidation
- 5. Data fusion
- 6. Data aggregation
- 10. Electric power consumption
- 11. Defect Detector
- 7. Dashboard
- 8. Hazard detection
- 9. Alert visualization (cars/trams)





NGAP/ADAS &
Predictive
Maintenance

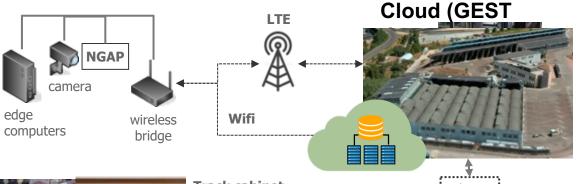






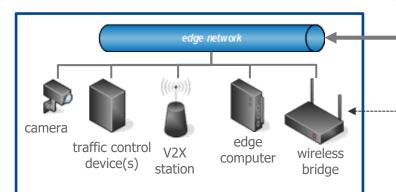


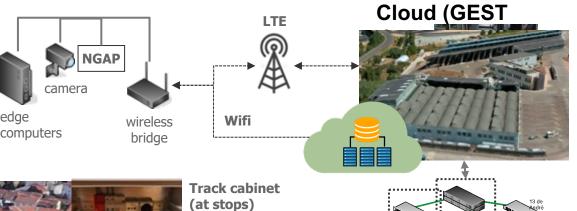




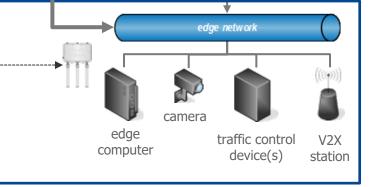


(e.g., pole)







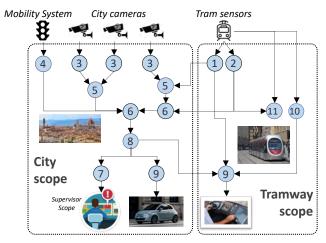


ATM Àrea de Barcelona Metropolità

The Compute Continuum



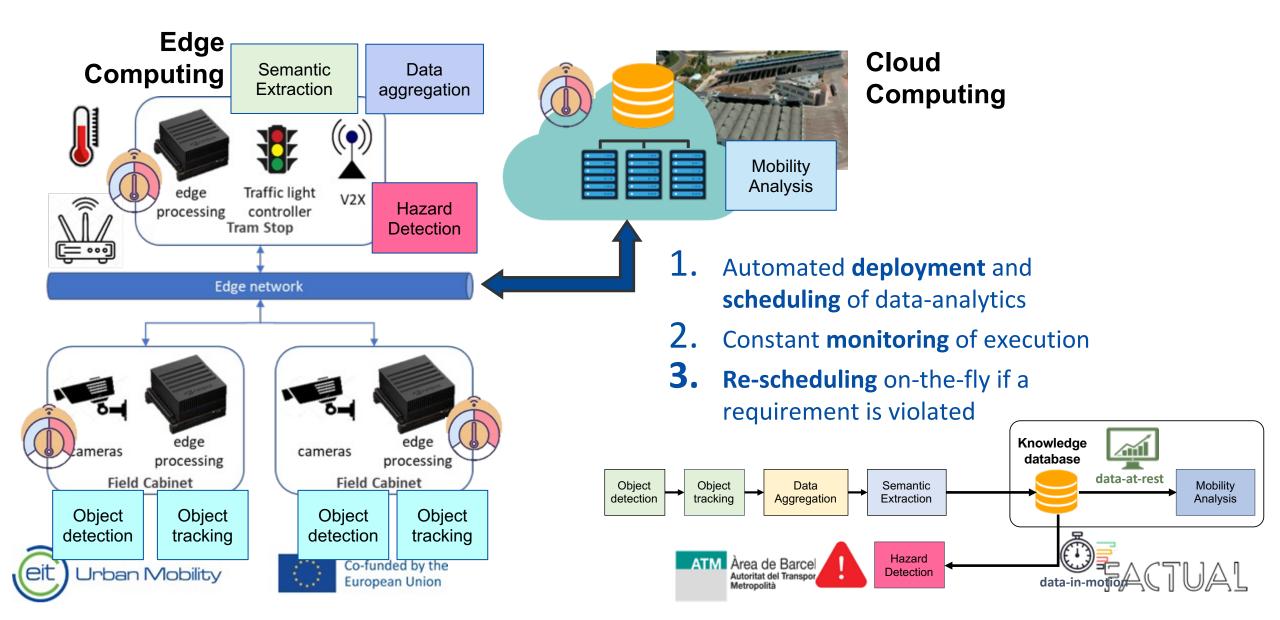
A Software Architecture for Extreme-ScaLe Big-Data AnalyticS in Fog CompuTIng Ecosystems



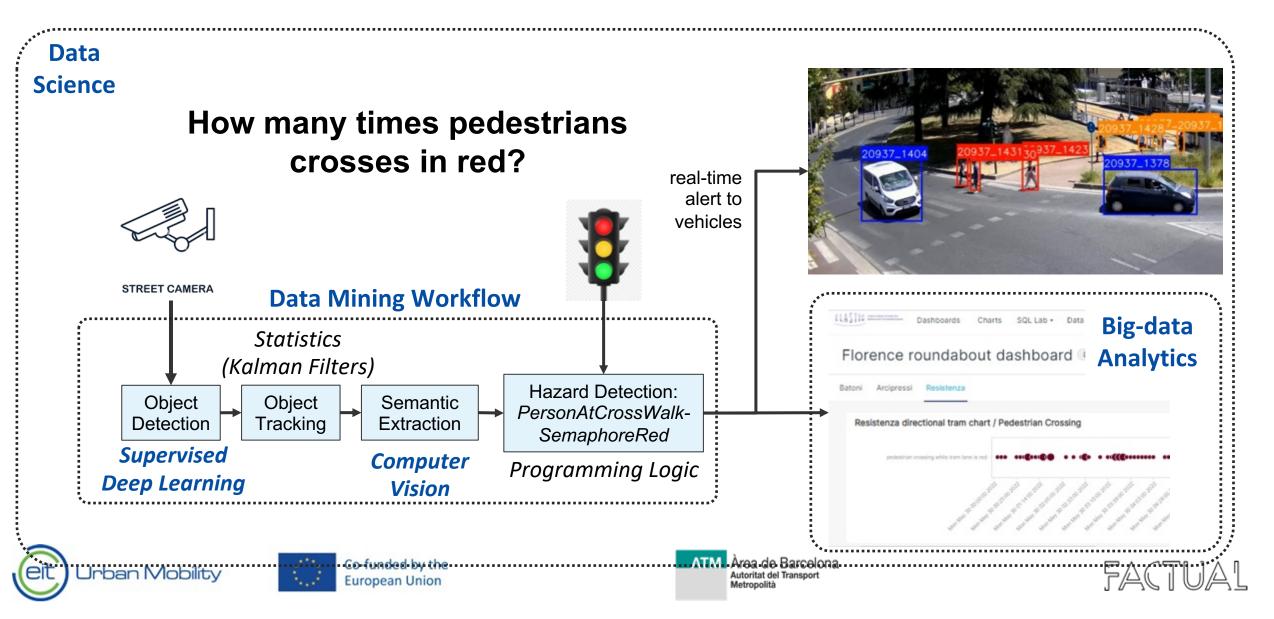




Towards a unified and secured compute continuum



Towards a unified and secured compute continuum



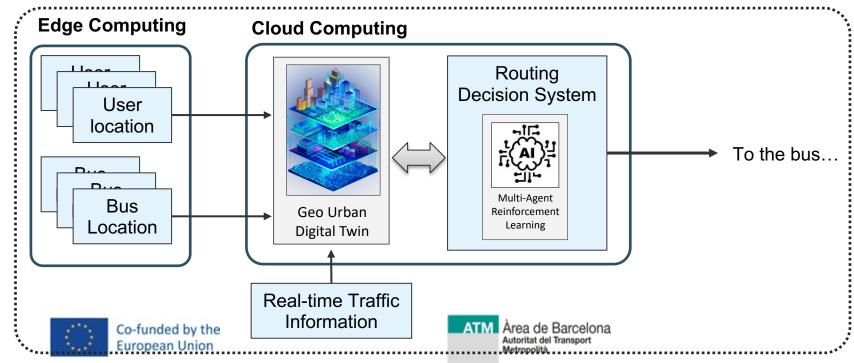
On-demand bus service:

Data Mining Workflow











FACTUAL

European Research Level



A Software Architecture for Extreme-ScaLe
Big-Data AnalyticS in Fog CompuTIng Ecosystems

















www.elastic-project.eu





















www.class-project.eu





European Research Level



A distributed data-mining software platform for extreme data across the compute continuum

https://extract-project.eu









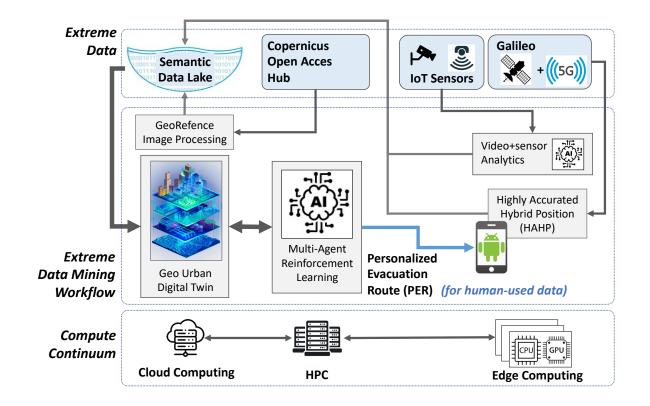
ikerlan







Personalized Evacuation Routing System to guide citizens in the city of Venice through a safe route in real time













Next Research Projects

PROXIMITY (National Project)(2022 - 2025)

- Create an integrated 5G and edge ecosystem to facilitate real-time connectivity between end users, sensors and compute continuum to increase the performance of mobility services
- Real-time safety application for road users, focused around tramway intersections in Barcelona
- Involved partners: BSC, Barcelona City Council and Tramway operator

AIRURBAN (National Project) (2022 - 2025)

- Improve accuracy and time-granularity of vehicle-related emission and air quality models, incorporating real-time traffic information
- Pilot infrastructure in Barcelona to monitor traffic around existing air quality monitoring stations, to develop and validate microscopic emission models and enhanced air quality prediction
- Involved partners: BSC, Barcelona City Council and Generalitat















La Digitalització de la Mobilitat

Data Science i Intel·ligència artificial

Eduardo Quiñones
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